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1	21	aspect with shear same image	USPAT; US-PGPUB	2003/10/15 13:52
2	427	pitch with roll with yaw same image	USPAT; US-PGPUB	2003/10/15 13:52
3	62	(pitch with roll with yaw same image) same position same orientation	USPAT; US-PGPUB	2003/10/15 13:53
4	96	(pitch with roll with yaw same image) same (reference or template)	USPAT; US-PGPUB	2003/10/15 13:53
5	16	((pitch with roll with yaw same image) same position same orientation) and ((pitch with roll with yaw same image) same (reference or template))	USPAT; US-PGPUB	2003/10/15 13:53
63	206	six adj degree adj freedom same three adj degree adj freedom	USPAT	2003/10/15 17:31
64	97	six adj degree adj freedom with three adj degree adj freedom	USPAT	2003/10/15 17:31
65	5	six adj degree adj freedom with three adj degree adj freedom same image	USPAT	2003/10/15 17:33
66	2	six adj degree adj freedom with three adj degree adj freedom with (align\$5 or registration or register)	USPAT	2003/10/15 17:36
67	0	six adj degree adj freedom with three adj degree adj freedom with (accurate or accuracy)	USPAT	2003/10/15 17:34
68	2	six adj degree adj freedom with three adj degree adj freedom same (accurate or accuracy)	USPAT	2003/10/15 17:40
69	7	six adj degree adj freedom with three adj degree adj freedom same (precision or precise)	USPAT	2003/10/15 17:36
70	8	six adj degree adj freedom same three adj degree adj freedom same (align\$5 or registration or register or position or orientation) same image	USPAT	2003/10/15 17:37
75	25	six adj degree adj freedom near2 (accurate or accuracy)	USPAT	2003/10/15 17:40
-	2168	six near degrees near freedom	USPAT	2003/10/10 09:38
-	4	(six near degrees near freedom) with fiducial	USPAT	2003/10/09 16:00
-	41	(six near degrees near freedom) same (marker or fiducial or target) same image	USPAT	2003/10/09 16:13
-	3	("4810091" "4845373" "4891829").PN.	USPAT	2003/10/09 16:04
-	4	("4281342" "4297725" "5008804" "5207003").PN.	USPAT	2003/10/09 16:11
-	208	werner-brian\$	USPAT	2003/10/09 17:11
-	5	("4748676" "4776464" "5072294" "5285273" "5452370").PN.	USPAT	2003/10/09 16:17
-	13	("3074634" "3639728" "3645391" "3648838" "3752312" "3801775" "3847346" "3902047" "4058217" "4065343" "4074852" "4403339" "4544064").PN.	USPAT	2003/10/09 16:23
-	11	5751843.URPN.	USPAT	2003/10/09 16:28
-	4	("4589140" "4658428" "4809341" "5046109").PN.	USPAT	2003/10/09 16:32
-	30	("4202008" "4238828" "4672564" "4678329" "4753569" "4834531" "4933864" "4988202" "5283560" "5422987" "5467404" "5502482" "5515447" "5550758" "5613048" "5675377" "5717782" "5724743" "5727078" "5731902" "5748505" "5751843" "5768443" "5825483" "5825666" "5831735" "5832139" "5850469" "5854880" "5856844").PN.	USPAT	2003/10/09 16:35

-	54	("2168566" "3562423" "3653769" "3801775" "3868565" "3898445" "3983474" "4054881" "4214266" "4219847" "4238828" "4396945" "4545576" "4553842" "4565999" "4613866" "4613942" "4631676" "4649504" "4672562" "4672564" "4719584" "4760851" "4788987" "4796187" "4834531" "4891630" "4897539" "4928175" "4933864" "4942538" "4956794" "4961138" "4988981" "5012049" "5095302" "5128671" "5128794" "5181181" "5198877" "5208763" "5214615" "5227985" "5230623" "5239463" "5276785" "5296871" "5297061" "5319387" "5329276" "5367373" "5473389" "5521843" "5691765") .PN.	USPAT	2003/10/09 16:36
-	11	("3757942" "3971917" "3990043" "4056711" "4254329" "4323773" "4374451" "4380696" "4439672" "4473883" "4514815") .PN.	USPAT	2003/10/09 16:42
-	88	4613942.URPN.	USPAT	2003/10/09 16:43
-	14	("3149522" "3513320" "3801775" "3805650" "3855887" "3881379" "4009466" "4140037" "4327615" "4435837" "4495845" "4544064" "4613942" "4721058") .PN.	USPAT USPAT	2003/10/09 16:52
-	88	4613942.URPN.	USPAT	2003/10/09 16:55
-	28	("3632995" "3801775" "4424588" "4695991" "4696049" "4718103" "4736109" "4745269" "4776464" "4874936" "4896029" "4924078" "4933865" "4947383" "4955062" "5103489" "5153418" "5153928" "5155343" "5189292" "5189711" "5191621" "5229591" "5241166" "5276315" "5291564" "5327171" "5329105") .PN.	USPAT USPAT	2003/10/09 17:02
-	3	("3513320" "3603728" "3693154") .PN.	USPAT	2003/10/09 17:03
-	5	("4805123" "4849679" "5537669" "5640200" "5793901") .PN.	USPAT	2003/10/09 17:09
-	198	((position or orientation) near object).ti.	USPAT	2003/10/09 17:11
-	27	((position or orientation) near object).ti.) and (fiducial or marker or target) same image	USPAT	2003/10/09 17:22
-	2	werner-brian\$ and substrate near tilt	USPAT	2003/10/09 17:24
-	20	("4248532" "4412121" "4811410" "4929845" "4959898" "4965665" "5048965" "5075559" "5097516" "5101442" "5127061" "5319567" "5450204" "5465152" "5471541" "5574801" "5644651" "5780866" "5987189" "6002793") .PN.	USPAT USPAT	2003/10/09 17:22
-	240	((position or orientation) same (marker or fiducial) same image same compar\$6 same (standard or reference or template)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/09 17:25
-	106	((position or orientation) same (marker or fiducial) same image same compar\$6 same (standard or reference or template)) and relative near position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/09 17:25
-	25	((position or orientation) same (marker or fiducial) same image same compar\$6 near (standard or reference or template)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/09 17:30

-	2	(position or orientation).ti. and (marker or fiducial) same image same compar\$6 same (standard or reference or template) with (yaw or rotation or skew)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/09 17:31
-	14	aspect with shear with image	USPAT	2003/10/10 09:42
-	2	aspect same shear same image same (fiducial or mark or target)	USPAT	2003/10/10 09:42
-	5	("4805123" "4849679" "5537669" "5640200" "5793901").PN.	USPAT	2003/10/10 09:43
-	25	rotat\$5 with translat\$5 with scale with (template or model or reference) with image	USPAT	2003/10/10 14:10
-	4	("5227830" "5311600" "5333210" "5351311").PN.	USPAT	2003/10/10 09:49
-	3665	(position or orientation) near estimat\$5	USPAT	2003/10/10 14:09
-	10106	(position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image	USPAT	2003/10/10 14:36
-	10572	(rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference)	USPAT	2003/10/10 14:45
-	20	((position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image) same ((rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference))	USPAT	2003/10/10 14:23
-	404	(skew or shear or warp\$5) near (template or model or reference)	USPAT	2003/10/10 14:41
-	14186	(position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:31
-	5552	(rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference)	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:31
-	26	((position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image) same ((rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference))	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:33
-	0	werner-brian\$ and ego adj motion	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:34
-	0	werner-brian\$ and egomotion	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:34
-	0	werner-brian\$ and ego\$6	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:34
-	0	werner-brian\$	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:34
-	1	werner-brian\$ and ego adj motion	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:34
-	6	("4797942" "4799267" "5202928" "5259040" "5818959" "6047078").PN.	USPAT	2003/10/10 14:35
-	566	(skew or shear or warp\$5) near (template or model or reference)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:45

-	24292	(position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:36
-	6	((skew or shear or warp\$5) near (template or model or reference)) and ((position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:37
-	38	(skew or shear or warp\$5) near templates	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:37
-	239	(skew or shear) near (template or model or reference)	USPAT	2003/10/10 14:41
-	6	(skew or shear) near (template or reference) with stor\$5	USPAT	2003/10/10 14:42
-	80	(382/216).CCLS.	USPAT; US-PGPUB	2003/10/10 14:42
-	16124	(rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:45
-	342	((position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image) and ((rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 14:45
-	10	((position or orientation) near (detect\$4 or determin\$5 or estimat\$5) with image) and ((rotat\$5 or translat\$5 or scal\$5 or skew or warp\$5) near (template or model or reference))) and six adj degree adj freedom	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/10/10 16:30
-	1	("6173066").PN.	USPAT	2003/10/10 16:38
-	17	("4402053" "4473883" "4644585" "4654872" "4707647" "4712248" "4845765" "4876728" "4982438" "5040231" "5173946" "5220615" "5249035" "5263098" "5351310" "5422962" "5809171").PN.	USPAT USPAT	2003/10/10 16:30
-	1	("5621807").PN.	USPAT	2003/10/10 16:38
-	12	("4653109" "4674869" "4796997" "4971445" "4988189" "5005147" "5087916" "5109425" "5170352" "5243666" "5488675" "5557684").PN.	USPAT USPAT	2003/10/10 16:38

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Acoustics, Speech, and Signal Processing, 1988. ICASSP-88., 1988

International Conference on , 11-14 April 1988

Page(s): 948 -951 vol.2

[\[Abstract\]](#) [\[PDF Full-Text \(380 KB\)\]](#) **IEEE CNF****2 Pseudo-Euclidean morphological skeleton transform for machine vision***Zhou, Z.; Venetsanopoulos, A.N.;*

Acoustics, Speech, and Signal Processing, 1989. ICASSP-89., 1989

International Conference on , 23-26 May 1989

Page(s): 1695 -1698 vol.3

[\[Abstract\]](#) [\[PDF Full-Text \(272 KB\)\]](#) **IEEE CNF****3 Morphological skeleton transforms for determining position and orientation of pre-marked objects***Zhou, Z.; Smith, K.C.; Benhabib, B.; Safaee-Rad, R.;*

Communications, Computers and Signal Processing, 1989.

Conference Proceeding., IEEE Pacific Rim Conference on , 1-2 June 1989

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Shillington, K.R.; Jahans, P.A.; Buller, E.H.; Tunaley, J.K.E.;

Antennas and Propagation Society International Symposium, 1991.

AP-S. Digest , 24-28 June 1991

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2 High-resolution ISAR imaging of maneuvering targets by means of the range instantaneous Doppler technique: modeling and performance analysis

Berizzi, F.; Mese, E.D.; Diani, M.; Martorella, M.;

Image Processing, IEEE Transactions on , Volume: 10 Issue: 12 , Dec. 2001

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3 ISAR imaging of rolling, pitching and yawing targets

Berizzi, F.; Diani, M.;

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4 A novel model of the platform attitude drift for SAR

Song Hongjun; Zhu Minhui; Bai Youtian;
Geoscience and Remote Sensing, 1997. IGARSS '97. 'Remote Sensing - A Scientific Vision for Sustainable Development', 1997
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5 The limits of spatial resolution achievable using a 30 kHz multibeam sonar: model predictions and field results

Clarke, J.E.H.; Gardner, J.V.; Torresan, M.; Mayer, L.;
OCEANS '98 Conference Proceedings , Volume: 3 , 28 Sept.-1 Oct. 1998
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6 Rotation and direction judgment from visual images head-slaved in two and three degrees-of-freedom

Adelstein, B.D.; Ellis, S.R.;
Systems, Man and Cybernetics, Part A, IEEE Transactions on ,
Volume: 30 Issue: 2 , March 2000
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International Conference on , 8-13 May 1994
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Papanikolopoulos, N.P.; Nelson, B.J.; Khosla, P.K.;
Robotics and Automation, IEEE Transactions on , Volume: 11 Issue: 5
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Sachs, E.; Stoops, D.; Roberts, A.;
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Page(s): 1194 -1196 vol.3

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Balogh, A.; Springfield, J.; Maciunas, R.; Galloway, R.;
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5 Image-based robot navigation under the perspective model

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6 Machine vision system for the automatic identification of robot kinematic parameters

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Robotics and Automation, IEEE Transactions on , Volume: 17 Issue: 6
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Biomedical Engineering, IEEE Transactions on , Volume: 49 Issue: 10 , Oct. 2002

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4 Fusion of vision and gyro tracking for robust augmented reality registration

You, S.; Neumann, U.;

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8 Testing a stereo vision system for motion compensation

Tisdall, J.; Hall, M.; Larkum, T.; Broome, D.;

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